

Adaptive Ultrasound
Technology for the
Inspection of Variable
Geometry Composite
Material







Agenda

- 1. Introduction and evolution of NDE in the aviation industry
- 2. Complex geometry inspection challenges
- 3. Goals
- 4. Solution: Adaptive focusing
 - Design introduction & overview
 - Results
- 5. Conclusion & next steps



 UT technology & instruments have been used in a wide variaty of industries for NDE over the last 20 years

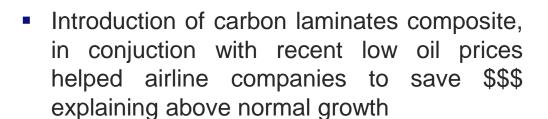






















- Consequently, aviation components manufacturers are facing new challenges :
 - Rise in production rate
 - Increasingly complex geometry
 - Lack of skilled operators
 - More demanding inspection requirements



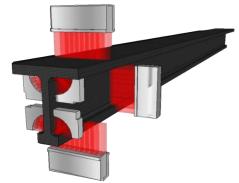




 Evolution of PA instruments help address these challenges

- Scalable PA instruments provide the following benefits
 - Faster inspection
 - Improved coverage for better repeatability
 - Improved radius inspection

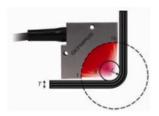


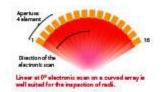






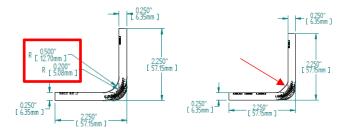
High data transfer rate







- Some <u>challenges remain</u> when full volumetric inspection of <u>varing</u> <u>geometry</u> (varying, flatten radius, tilted parts) is required.
- Today these parts are either inspected manually or via complex mechanical devices, that are error-prone, hard to configure and costly

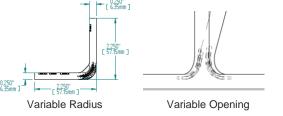




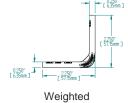


Challenges

- Inspection of carbon laminates parts with the following characteristics:
 - Variable radius
 - Variable opening angle



 Inspection of non-constant (weighted) radius generated by the manufacturing process



- Inspection of rounded flat surfaces generated by the manufacturing process
- Part vs probe alignment (curved and flat arrays)



Goals

- Improve & simplify the inspection of complex geometry components
 - Variable & weighted radius
 - Variable opening and twisted parts
- Flexible solution to allow inspection from :
 - Inside & outside radius
 - Flat surface



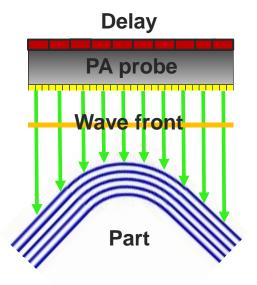
Performant solution

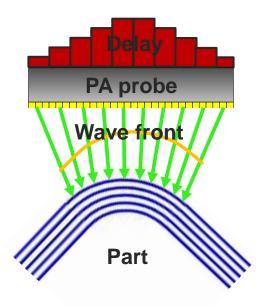
- Inspection speed has to be similar to what is achieve today with standard phased array
- Reliable & robust solution



Adaptive Focusing Solution Introduction

What is the most desirable configuration?

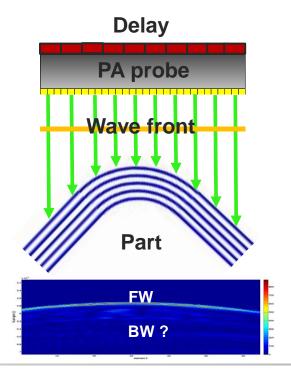


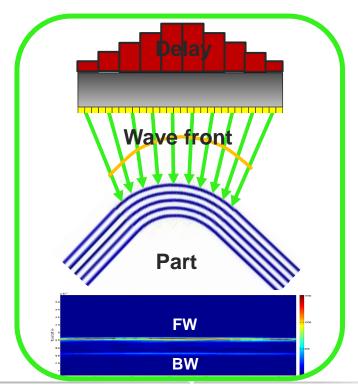




Adaptive Focusing Solution Introduction

What is the most desirable configuration?

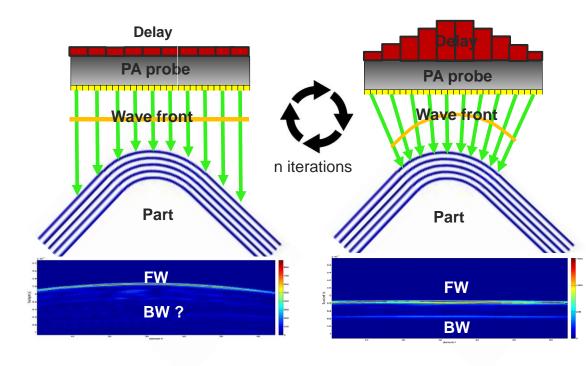






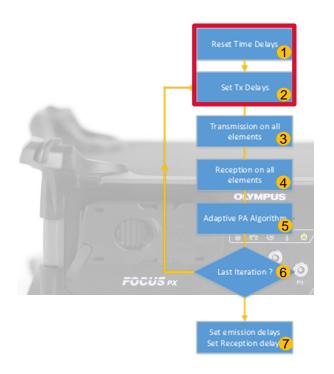
Adaptive Focusing Solution Introduction

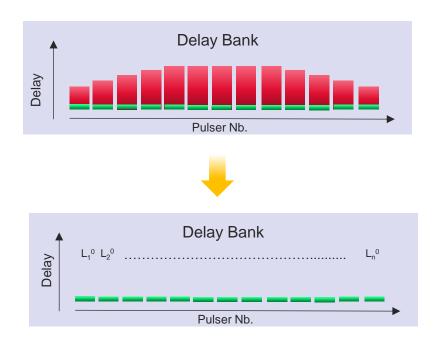
 Adaptive Focusing is an iterative process that allows the transmission of a wavefront parallel to the part



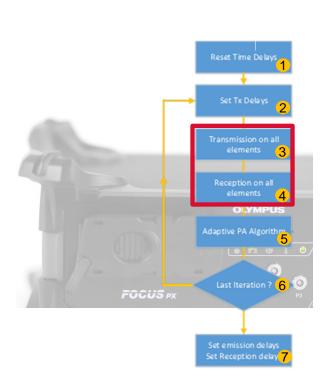


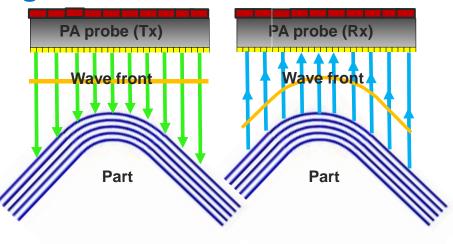


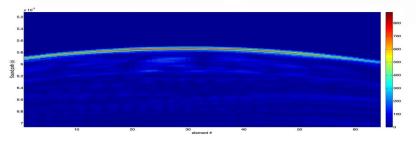






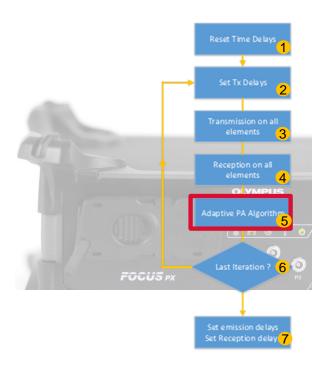








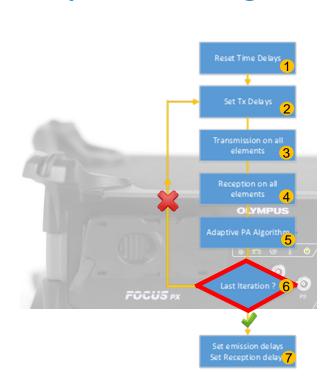


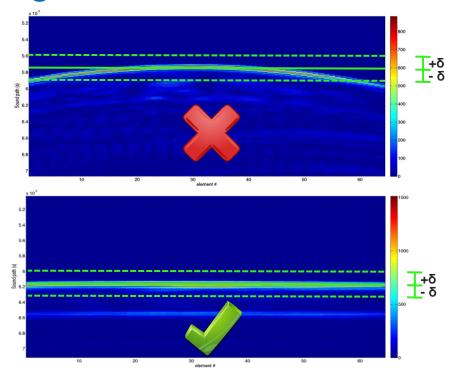








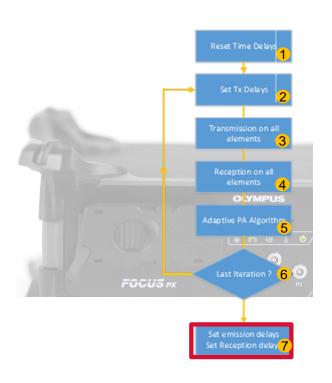


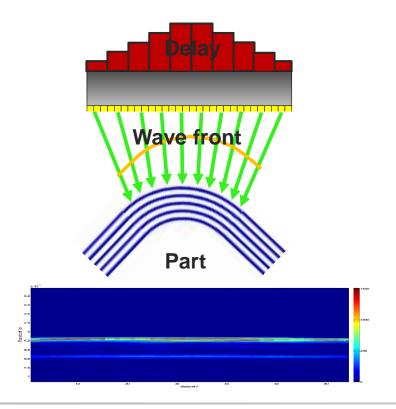


Is the frontwall corrected within a predefined tolerance (δ) ?





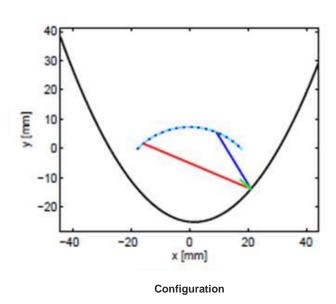


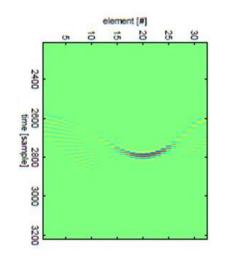


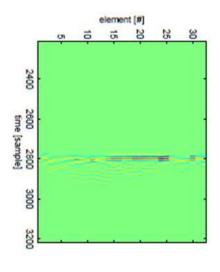




Simulation







First iteration

Last iteration





Case 1 : Varying radius

Part & Scan Parameters

Geometry: L shape

Radius : 5mm to 10mm

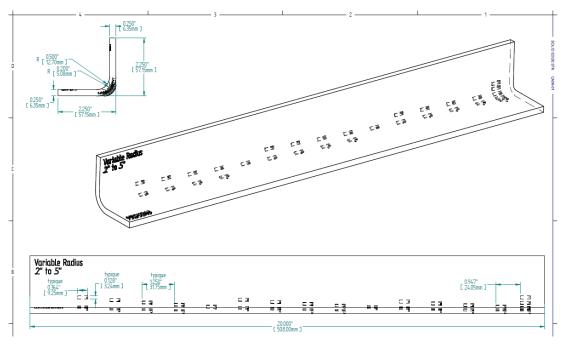
Scan : External face

Probe: 5CC25-32R4



• Wedge : SR4-IE90







Case 1 : Varying radius

Results

- Detection
 - 28\30 with AF
 - 20\30 without AF
- Defect Size
 - 77 mm² with AF
 - 66 mm² without AF
- SNR
 - 23 dB with AF
 - 9 dB without AF

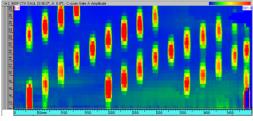


Figure 1: Amplitude C-Scan with AF

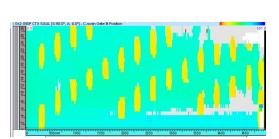


Figure 2: Position C-Scan with AF

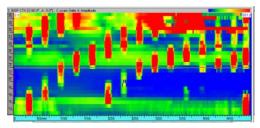


Figure 3: Amplitude C-Scan without AF

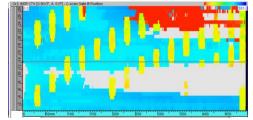


Figure 4: Position C-Scan without AF





Case 2 : Varying radius

Part & Scan Parameters

Geometry: L shape

Radius : 5mm to 10mm

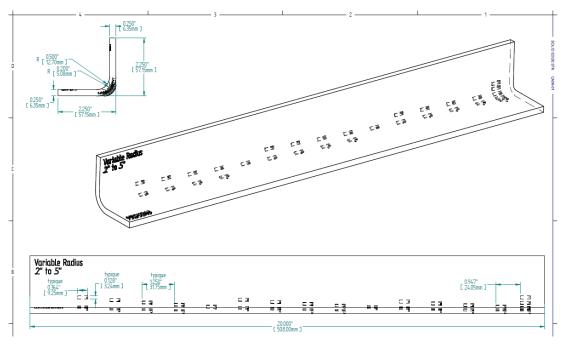
Scan : Internal face

Probe : 5CC25-32R4



• **Wedge** : SR4-IE90









- Case 2 : Varying radius
- Results
 - Detection
 - 26\30 with AF
 - 18\30 without AF
 - Defect Size (area in mm)
 - 91 mm² with AF
 - 84 mm² without AF
 - SNR
 - 22 dB with AF
 - 22 dB without AF

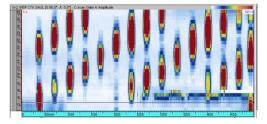


Figure 1: Amplitude C-Scan with AF

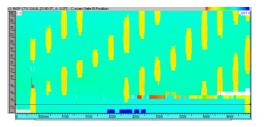


Figure 2: Position C-Scan with AF

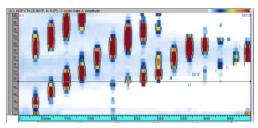


Figure 3: Amplitude C-Scan without AF

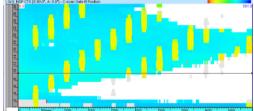


Figure 4 : Position C-Scan without AF





Case 3 : Varying & weighted radius

Part & Scan Parameters

Geometry: L shape

• Radius : 5mm to 10mm

Weighted : 10mm

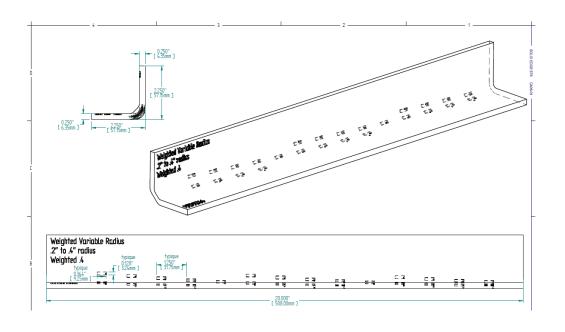
Scan : Internal face

Probe : 5CC25-32R4



• **Wedge** : SR4-IE90









- Case 3 : Varying & weighted radius
- Results
 - Detection
 - 26\30 with AF
 - 13\30 without AF
 - Defect Size (area in mm)
 - 90 mm² with AF
 - 88 mm² without AF
 - SNR
 - 12 dB with AF
 - 0 dB without AF

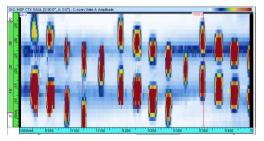


Figure 1: Amplitude C-Scan with AF

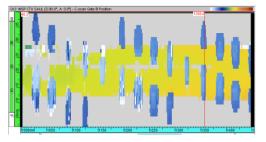


Figure 2: Position C-Scan with AF

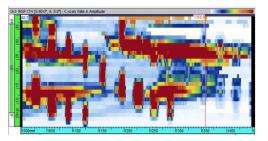


Figure 3: Amplitude C-Scan without AF

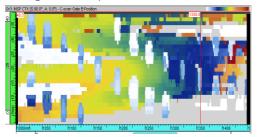


Figure 4 : Position C-Scan without AF





Productivity

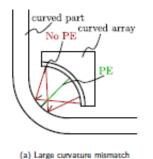
Parameters	
Nb. Of Elements	32
Aperture Size	4
Aperture Steps	1
Water path	25 mm
Material Thickness	8.5 mm
Material Velocity	2700 m\s
Nb. Of iterations	5

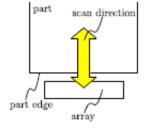
PRF with AF	PRF without AF
300 Hz	517 Hz



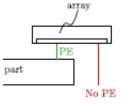


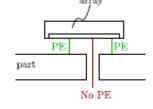
Reliability and ruggedness





(b) Edge in/Edge out





(c) Hanging probe

(d) Holes



Conclusion

<u>Improve & simplify</u> the inspection of complex geometry components



- Variable & weighted radius
- Variable opening and twisted parts
- Flexible solution allowing inspection from



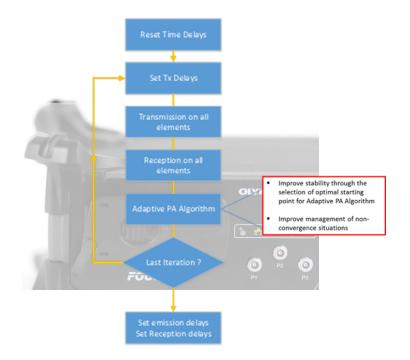
- Inside & outside radius
- Flat surface
- Performant solution
 - Inspection speed has to be similar to what is acheive today with standard phased array
- Reliable & robust solution

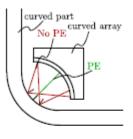




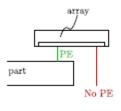


Conclusion & Next Steps

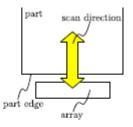




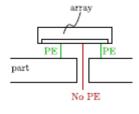
(a) Large curvature mismatch



(c) Hanging probe



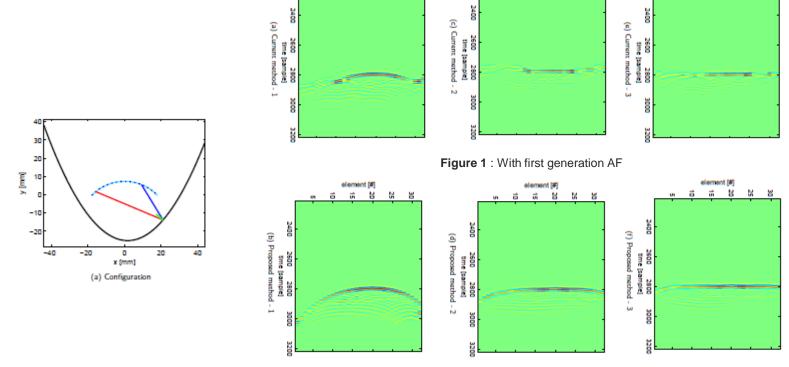
(b) Edge in/Edge out



(d) Holes

is 23 25 25

Conclusion & Next Steps



15 15

Figure 2: With second generation AF

5 22 25 25



